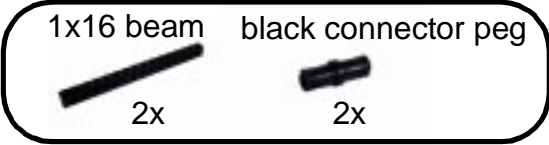


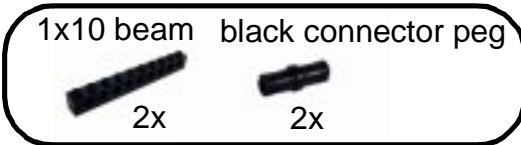
Building Instructions

Experiment 1

1 1x16 beam 2x black connector peg 2x



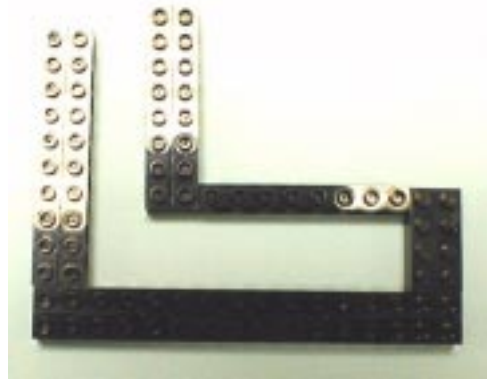

2 1x10 beam 2x black connector peg 2x



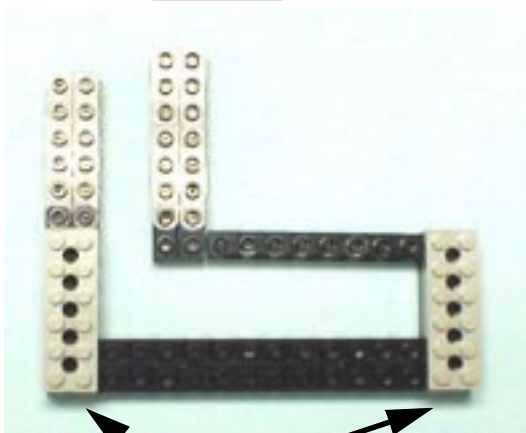
3 1x8 beam 2x black connector peg 2x



4 1x8 beam 1x 2x4 brick 1x

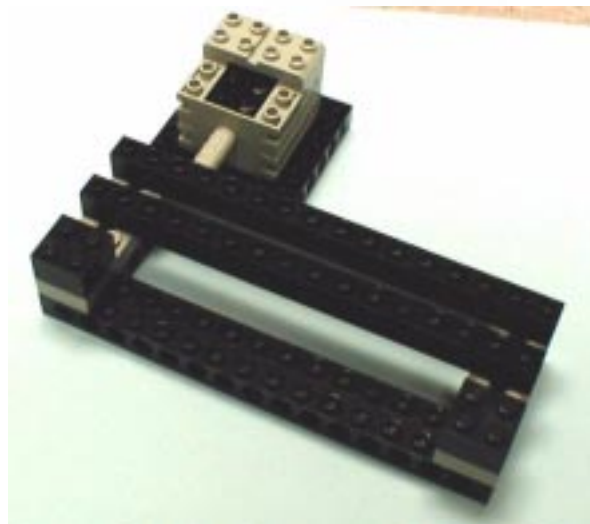
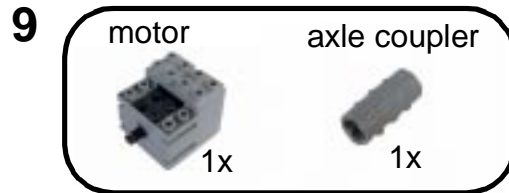
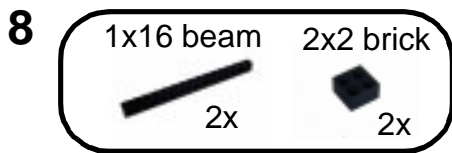
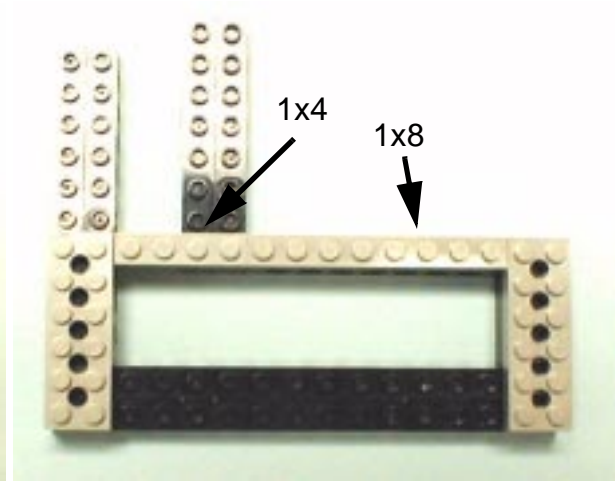
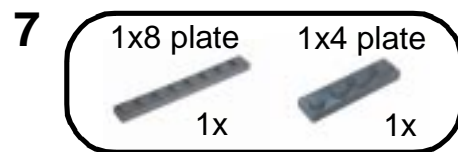
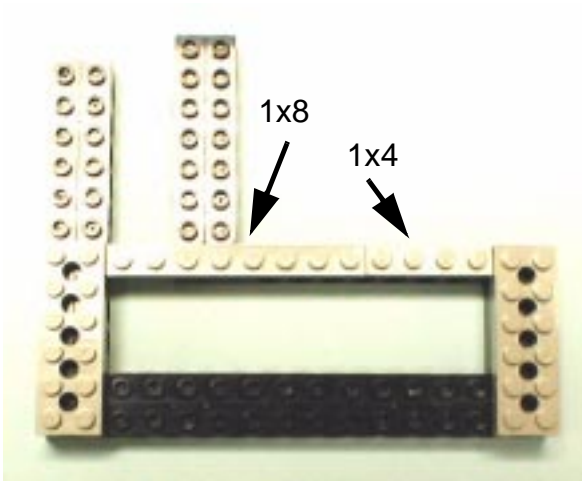
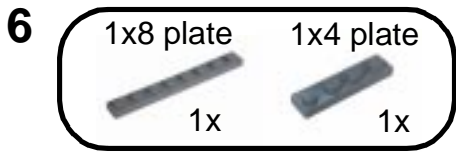


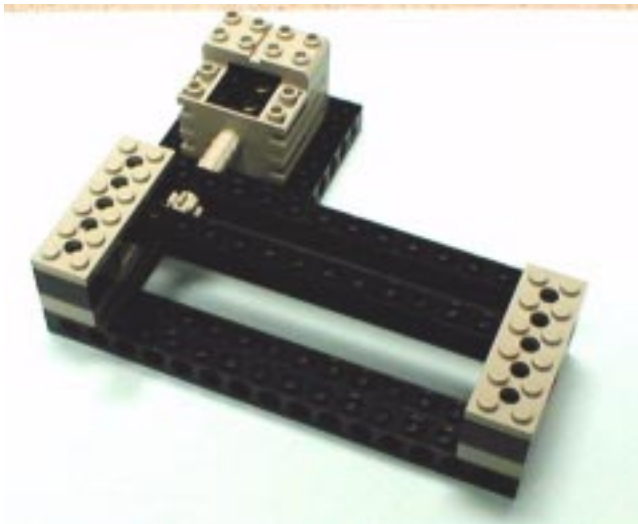
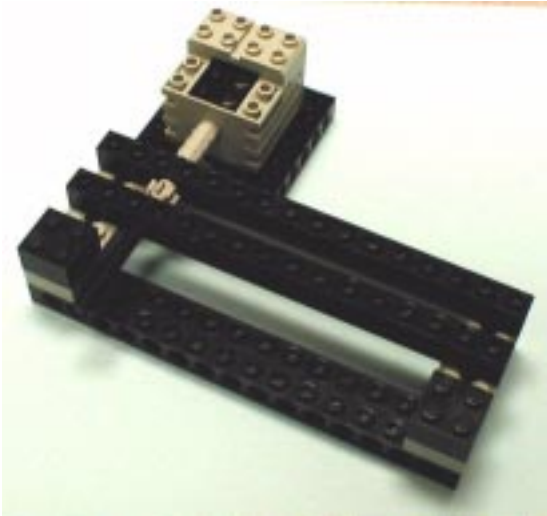
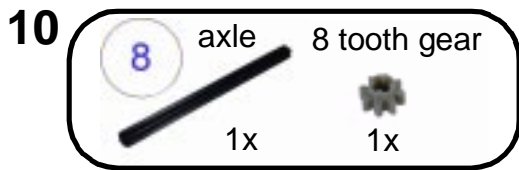
5 2x6 plate 4x



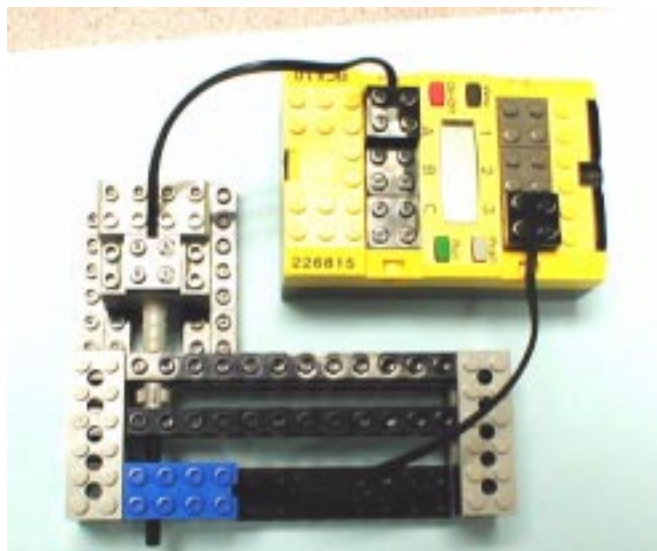
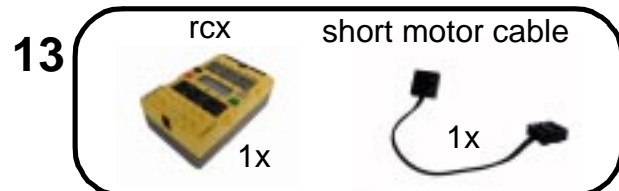
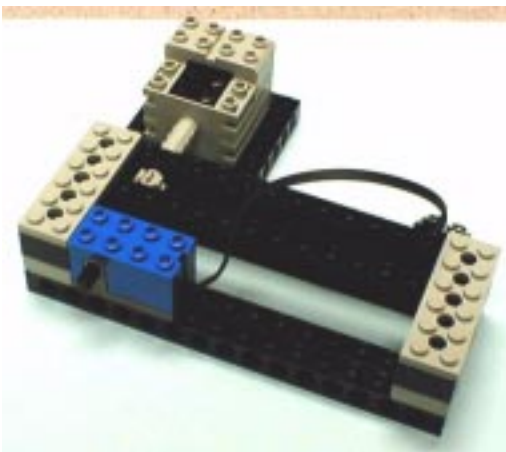
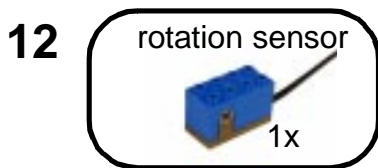
double plates

Place pieces in this configuration.





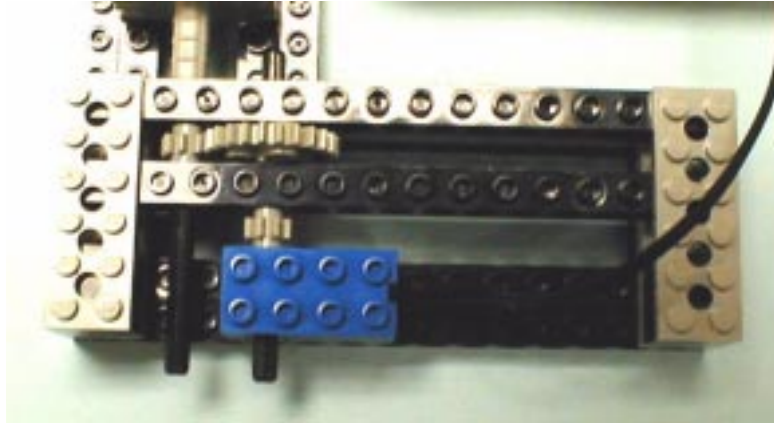
make sure there is not too much friction between the gear and beams.



connect the cables as exactly as shown

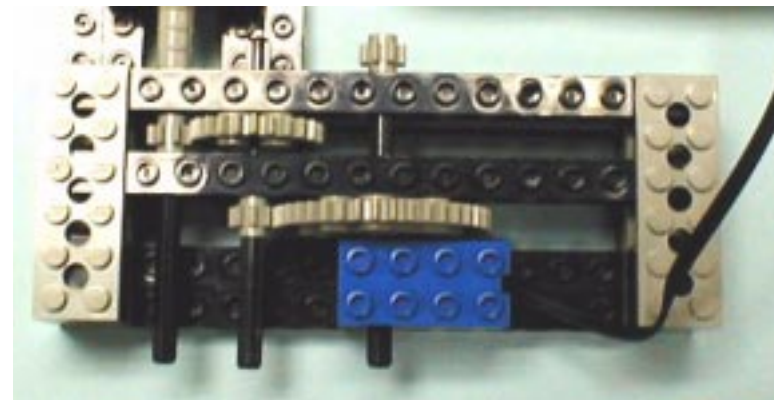
Experiment 2

1



Experiment 3

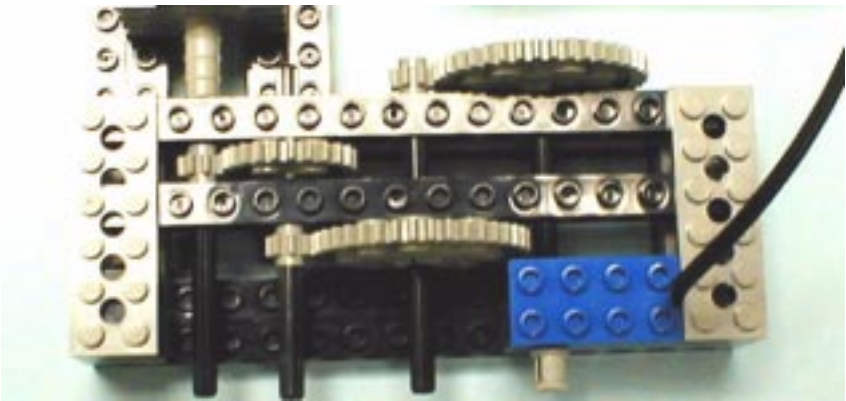
1



Experiment 4

1

	axle		full bushing		40 tooth gear
	1x		1x		1x



RoboLab Program

